

# PATENT COOPERATION TREATY

PCT

## NOTIFICATION OF ELECTION

(PCT Rule 61.2)

From the INTERNATIONAL BUREAU

To:

United States Patent and Trademark  
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Washington, DC 20231  
ÉTATS-UNIS D'AMÉRIQUE

in its capacity as elected Office

<b>Date of mailing (day/month/year)</b> 08 July 1999 (08.07.99)	<b>Applicant's or agent's file reference</b> 21513
<b>International application No.</b> PCT/AU98/00934	<b>Priority date (day/month/year)</b> 07 November 1997 (07.11.97)
<b>International filing date (day/month/year)</b> 09 November 1998 (09.11.98)	
<b>Applicant</b> MASON, James, Herbert	

1. The designated Office is hereby notified of its election made:

☒ in the demand filed with the International Preliminary Examining Authority on:  
28 May 1999 (28.05.99)

☐ in a notice effecting later election filed with the International Bureau on:

2. The election ☒ was  
☐ was not

made before the expiration of 19 months from the priority date or, where Rule 32 applies, within the time limit under Rule 32.2(b).

<b>The International Bureau of WIPO</b> 34, chemin des Colombettes 1211 Geneva 20, Switzerland Facsimile No.: (41-22) 740.14.35	<b>Authorized officer</b> C. Carrié Telephone No.: (41-22) 338.83.38
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## PATENT COOPERATION TREATY

From the INTERNATIONAL BUREAU

**PCT**NOTIFICATION OF WITHDRAWAL  
OF PRIORITY CLAIM(PCT Rule 90bis.3 and  
Administrative Instructions, Section 415(a) and (b))

To:

BALDWIN SHELSTON WATERS  
60 Margaret Street  
Sydney, NSW 2000  
AUSTRALIE

Date of mailing (day/month/year) 09 May 2000 (09.05.00)	
Applicant's or agent's file reference 21513	IMPORTANT NOTIFICATION
International application No. PCT/AU98/00934	International filing date (day/month/year) 09 November 1998 (09.11.98)
Applicant MASON, James, Herbert	

1. The applicant is hereby notified that the priority claim made in the international application has been withdrawn in accordance with a notice of withdrawal received from the applicant on:

05 May 2000 (05.05.00)

The attention of the applicant is drawn to the fact that the withdrawal of the priority claim will result in the re-calculation of time limits which have not already expired (see Rule 90bis.3(d)).

2. ☐ In the case where multiple priorities have been claimed, the above action relates to the following priority claim(s):

3. A copy of this notification has been sent to the receiving Office and to:

- ☐ the International Searching Authority (where the international search report has not yet been issued)
- ☒ the designated Offices (which have already been notified of the receipt of the record copy)
- ☐ the International Preliminary Examining Authority

The International Bureau of WIPO 34, chemin des Colombettes 1211 Geneva 20, Switzerland Facsimile No. (41-22) 740.14.35	Authorized officer Maria Victoria CORTIELLO Telephone No. (41-22) 338.83.38
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REC'D 07 MAR 2000

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Applicant's or agent's file reference 21513	<b>FOR FURTHER ACTION</b>	See Notification of Transmittal of International Preliminary Examination Report (Form PCT/IPEA/416).
International application No. <b>PCT/AU98/00934</b>	International filing date ( <i>day/month/year</i> ) 9 November 1998	Priority Date ( <i>day/month/year</i> ) 7 November 1997
International Patent Classification (IPC) or national classification and IPC  <b>Int. Cl. <sup>7</sup> G01B 5/004, 5/02, 5/14, 5/25, B60S 5/00</b>		
Applicant <b>James Herbert MASON</b>		

1.	This international preliminary examination report has been prepared by this International Preliminary Examining Authority and is transmitted to the applicant according to Article 36.	
2.	This REPORT consists of a total of <b>3</b> sheets, including this cover sheet.  <input type="checkbox"/> This report is also accompanied by ANNEXES, i.e., sheets of the description, claims and/or drawings which have been amended and are the basis for this report and/or sheets containing rectifications made before this Authority (see Rule 70.16 and Section 607 of the Administrative Instructions under the PCT).  These annexes consist of a total of      sheet(s).	
3.	This report contains indications relating to the following items:  I <input checked="" type="checkbox"/> Basis of the report II <input type="checkbox"/> Priority III <input type="checkbox"/> Non-establishment of opinion with regard to novelty, inventive step and industrial applicability IV <input type="checkbox"/> Lack of unity of invention V <input checked="" type="checkbox"/> Reasoned statement under Article 35(2) with regard to novelty, inventive step or industrial applicability; citations and explanations supporting such statement VI <input type="checkbox"/> Certain documents cited VII <input type="checkbox"/> Certain defects in the international application VIII <input type="checkbox"/> Certain observations on the international application	

Date of submission of the demand 28 May 1999	Date of completion of the report 1 March 2000
Name and mailing address of the IPEA/AU  AUSTRALIAN PATENT OFFICE PO BOX 200, WODEN ACT 2606, AUSTRALIA E-mail address: pct@ipaaustralia.gov.au Facsimile No. (02) 6285 3929	Authorized Officer  <b>M.E. DIXON</b>  Telephone No. (02) 6283 2194

**I Basis of the report**

1. With regard to the elements of the international application:\*
- ☒ the international application as originally filed.
- ☐ the description,        pages , as originally filed,  
                                         pages , filed with the demand,  
                                         pages , filed with the letter of .
- ☐ the claims,        pages , as originally filed,  
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- ☐ the drawings,        pages , as originally filed,  
                                         pages , filed with the demand,  
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- ☐ the sequence listing part of the description:  
                                         pages , as originally filed  
                                         pages , filed with the demand  
                                         pages , filed with the letter of .
2. With regard to the language, all the elements marked above were available or furnished to this Authority in the language in which the international application was filed, unless otherwise indicated under this item.  
These elements were available or furnished to this Authority in the following language which is:
- ☐ the language of a translation furnished for the purposes of international search (under Rule 23.1(b)).
- ☐ the language of publication of the international application (under Rule 48.3(b)).
- ☐ the language of the translation furnished for the purposes of international preliminary examination (under Rules 55.2 and/or 55.3).
3. With regard to any nucleotide and/or amino acid sequence disclosed in the international application, was on the basis of the sequence listing:
- ☐ contained in the international application in written form.
- ☐ filed together with the international application in computer readable form.
- ☐ furnished subsequently to this Authority in written form.
- ☐ furnished subsequently to this Authority in computer readable form.
- ☐ The statement that the subsequently furnished written sequence listing does not go beyond the disclosure in the international application as filed has been furnished.
- ☐ The statement that the information recorded in computer readable form is identical to the written sequence listing has been furnished
4. ☐ The amendments have resulted in the cancellation of:
- ☐ the description,        pages
- ☐ the claims,        Nos.
- ☐ the drawings,        sheets/fig.
5. ☐ This report has been established as if (some of) the amendments had not been made, since they have been considered to go beyond the disclosure as filed, as indicated in the Supplemental Box (Rule 70.2(c)).\*\*

\* Replacement sheets which have been furnished to the receiving Office in response to an invitation under Article 14 are referred to in this report as "originally filed" and are not annexed to this report since they do not contain amendments (Rules 70.16 and 70.17).

\*\* Any replacement sheet containing such amendments must be referred to under item 1 and annexed to this report

**V. Reasoned statement under Article 35(2) with regard to novelty, inventive step or industrial applicability; citations and explanations supporting such statement**

**1. Statement**

Novelty (N)	Claims 6-8, 10-17, 20-26	YES
	Claims 1-5, 9, 18, 19	NO
Inventive step (IS)	Claims 10-17, 20-26	YES
	Claims 1-9, 18, 19	NO
Industrial applicability (IA)	Claims 1-26	YES
	Claims	NO

**2. Citations and explanations (Rule 70.7)**

**NOVELTY**

- US 5553389 discloses a device for adjusting vehicle wheel toe and having sensor units 19, 21 for measurement of toe, signal emitter 25, memory 33 to store specification information, processor 3 to subtract specification value from measured value to generate a variation signal which is stored and displayed - see in particular col 2 line 66 - col 4 line 33. All the features of claim 1 are disclosed. Reference to "structural" in the last line of the claim is not considered significant since wheels are part of the overall structure of the vehicle.
- US 5388057 - similarly to the above, this document discloses the features of claim 1, i.e. measuring means, output signal generation means, storage means, comparator means and display means as well as recordal means (printer 8) - thereby also disclosing the features of claims 18, 19.
- US 4977542 discloses all the features of claims 1-5, 9. See the whole specification and in particular col 6 line 27 - col 7 line 41.
- US 4811250 discloses all the features of claims 1, 18, 19. See col 6 line 38 - col 7 line 13, figs 1A, 1B.
- US 4381548 discloses all the features of claim 1. See col 2 line 54 - col 5 line 33.
- EP 0769675 discloses all the features of claims 1, 18, 19. See col 2 line 18 - col 4 line 58, figs.
- EP 0566239 discloses all the features of claim 1. See col 4 lines 5 - 41, fig 4.
- JP 5-126559 discloses all the features of claim 1.

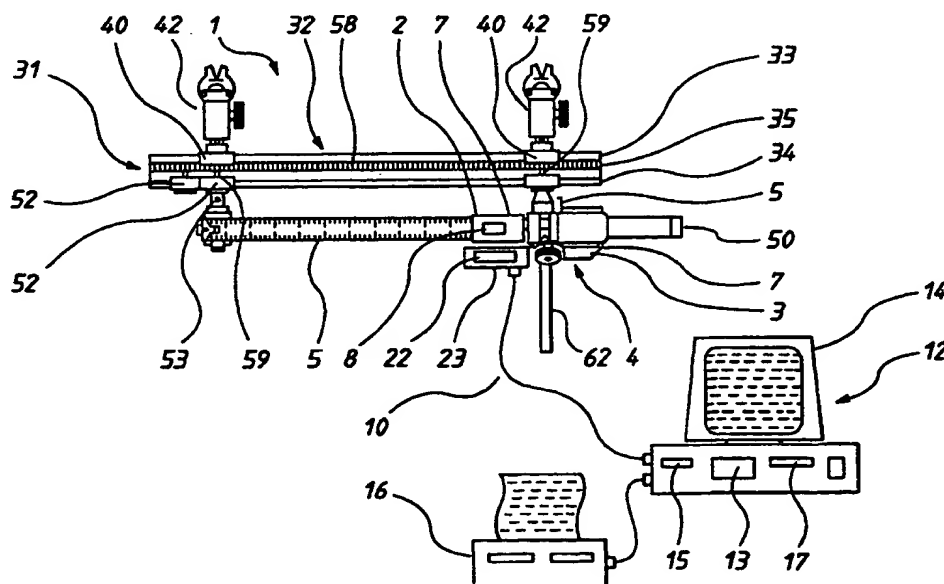
**INVENTIVE STEP**

- In view of US 4977524 claims 6-8 lack inventive step since the features of these claims would be obvious to a person skilled in the art.



## INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

<b>(51) International Patent Classification <sup>6</sup>:</b> <b>G01B 5/004, 5/02, 5/14, 5/25, B60S 5/00</b>	<b>A1</b>	<b>(11) International Publication Number:</b> <b>WO 99/24781</b> <b>(43) International Publication Date:</b> 20 May 1999 (20.05.99)
<b>(21) International Application Number:</b> PCT/AU98/00934 <b>(22) International Filing Date:</b> 9 November 1998 (09.11.98) <b>(30) Priority Data:</b> PP 0235 ✓ 7 November 1997 (07.11.97) AU <b>(71)(72) Applicant and Inventor:</b> MASON, James, Herbert [AU/AU]; 2 Wellington Street, Narrabeen, NSW 2101 (AU). <b>(74) Agent:</b> BALDWIN SHELSTON WATERS; 60 Margaret Street, Sydney, NSW 2000 (AU).		<b>(81) Designated States:</b> AL, AM, AT, AU, AZ, BA, BB, BG, BR, BY, CA, CH, CN, CU, CZ, DE, DK, EE, ES, FI, GB, GD, GE, GH, GM, HR, HU, ID, IL, IS, JP, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MD, MG, MK, MN, MW, MX, NO, NZ, PL, PT, RO, RU, SD, SE, SG, SI, SK, SL, TJ, TM, TR, TT, UA, UG, US, UZ, VN, YU, ZW, ARIPO patent (GH, GM, KE, LS, MW, SD, SZ, UG, ZW), Eurasian patent (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European patent (AT, BE, CH, CY, DE, DK, ES, FI, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE), OAPI patent (BF, BJ, CF, CG, CI, CM, GA, GN, GW, ML, MR, NE, SN, TD, TG).  <b>Published</b> <i>With international search report.</i>

**(54) Title:** COMPUTERISED VEHICLE ALIGNMENT SYSTEM**(57) Abstract**

A vehicle alignment gauging system (1) including measuring means (2, 3), output signal generation means adapted to generate an output signal corresponding to dimensions indicated by the measuring means, storage means (15) to store reference data corresponding to standard reference dimensions for a selected vehicle, comparator means to compare the output signal with a selected reference dimension from the storage means and to generate an error signal indicative of the variation therebetween, and variation display means (22) to provide a visual indication of the magnitude of the variation, thereby in use to provide a quantitative indication of structural misalignment.

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**TITLE: COMPUTERISED VEHICLE ALIGNMENT SYSTEM****FIELD OF THE INVENTION**

The present invention relates to a system for measuring, and assisting in the alignment and repair, of damaged or potentially damaged structural members.

5       The invention has been developed primarily for use in the automotive industry, and more particularly in the panel beating trade. The invention will therefore be described with reference to this application. It will be appreciated, however, that the invention is not limited to this particular field of use.

**10   BACKGROUND OF THE INVENTION**

In the manufacture of motor vehicles, it is common practice to provide specific datum points in the structure to assist in "jigging" the vehicle during manufacture, and in checking the dimensional accuracy of the finished product. These datum points can take various forms such as holes in the chassis, male or female threaded members such as bolt  
15   heads, nuts or studs, and other formations such as pins, lugs and suspension mounting points. They may be spaced apart in both vertical and horizontal planes. The datum points vary significantly from model to model according to various design parameters and practical convenience.

Numerous types of known apparatus are designed to permit measurements to be  
20   taken between various datum points on a given vehicle. By comparison with reference charts provided by the manufacturer, or with corresponding measurements taken on the opposite side of the vehicle, such equipment provides an absolute or at least a relative indication of the extent of structural misalignment. This facilitates the evaluation and



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repair of damaged or potentially damaged vehicles by panel beaters. Most known devices, however, have been found to be inadequate in various respects.

One type of prior art device consists in a peripheral reference frame rotatably or otherwise connected to a floor mounted anchorage assembly, so as to extend generally  
5 around the vehicle. Such devices are not adapted for direct connection to the datum points on the vehicle, and so are not able to provide an accurate or direct quantitative correlation between the various datum points and the manufacturers specifications. At best, they provide a relative measure of the inconsistency between comparable points on opposite sides of the vehicle. This is of little assistance if both sides of the vehicle have  
10 been damaged, and in any case will not reveal distortion in certain planes. Moreover, such devices tend to be structurally flimsy, and are inherently prone to excessive deflection, particularly adjacent the front and rear extremities of the vehicle where accurate measurement is critical. Further, in such measurement systems, it is difficult or impossible to align the vehicle precisely with the floor mounted anchorage assembly.  
15 For these reasons, such devices are often not capable even of providing consistent comparative measurements between corresponding points on the vehicle, which is necessary to provide a reliable measure of the degree of misalignment to the required level of accuracy.

Other known devices are adapted for direct connection to specific datum points,  
20 and so are capable of correlating measurements between these points on the vehicle with dimensional specifications provided by the manufacturer. However, most such devices are complex, expensive, cumbersome, involve a relatively large number of components, and are generally difficult and time consuming to use. Furthermore, most known

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devices of this type are capable only of providing quantitative measurements between longitudinally or transversely spaced datum points. As such, they cannot usually detect parallelogram type deflection in the vehicle frame, or deformation in the body panels beyond certain datum points.

5        Some devices are known which are adapted for direct connection to the datum points on the vehicle and are also capable of providing diagonal and other non-orthogonal measurements. There is a significant remaining difficulty, however, in that many of the measurements provided on vehicle manufacturers' specification sheets are defined relative to arbitrary reference planes, which are usually different from the  
10    inherent reference planes associated with the measurement apparatus. Consequently, as each measurement is taken, it is necessary for the operator to perform an arithmetic calculation in order to correlate the actual measurements taken with the reference data and thereby ascertain the absolute magnitude of the extent of misalignment. These calculations can become complex, particularly where a number of correction factors or  
15    cumulative measurements are involved, and this gives rise to a significant possibility for human error.

Partly because of this difficulty dedicated jigs, frames or the like are sometimes manufactured for certain common makes and models of vehicle. However, these tend to be expensive and require considerable set up time. Consequently, such devices tend  
20    only to be economically viable in connection with major repairs and are not readily applicable to a wide range of vehicles.

A further difficulty with known systems is that there is no means for verifying after the event the extent of initial misalignment or the deviation from the

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manufacturer's specifications after repair. As a result, vehicle repairs can be substandard and once the vehicle has been reassembled, the accuracy of the repairs can be difficult to check. Insurance companies are increasingly requiring quality assurance procedures to provide a means of confirming the damage to, and the subsequent rectification of, the vehicle in quantitative terms. Currently known systems do not enable this to be done in a convenient, accurate, reliable and cost effective manner.

It is an object of the present invention to overcome or substantially ameliorate one or more of the disadvantages of the prior art, or at least to provide a useful alternative.

## 10 DISCLOSURE OF THE INVENTION

Accordingly, the invention provides a vehicle alignment gauging system including measuring means, output signal generation means adapted to generate an output signal corresponding to dimensions indicated by the measuring means, storage means to store reference data corresponding to standard reference dimensions for a selected vehicle, comparator means to compare the output signal with a selected reference dimension from the storage means and to generate an error signal indicative of the variation therebetween, and variation display means to provide a visual indication of the magnitude of the variation, thereby in use to provide a quantitative indication of structural misalignment.

20 Preferably, the measuring means include an extendable measuring tape, and the output signal is indicative of an operative or extended length of the tape.

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Preferably, the output signal generation means include a position transducer adapted to generate the output signal in the form of an electric current or voltage, indicative of the extended length of the measuring tape.

Preferably, the system further includes output signal display means to display a  
5 visual indication of the extended length of the measuring tape according to the output signal, thereby to permit visual correlation between indicia on the measuring tape and the output signal.

Preferably, the system includes a pair of said measuring tapes, one being adapted for measurement in horizontal planes and the other being adapted for measurement in  
10 vertical planes. Preferably, the measuring tapes are supported in mutually orthogonal relationship in or on a common housing.

Preferably, the output signal display means associated with each of the measuring tapes is disposed on or adjacent the housing. The housing preferably also includes a "black box" containing electronic control and signal processing circuitry.

15 Preferably, the storage means is associated with a portable computer and may include a compact disc, a floppy disk, an internal disk drive, an external disk drive, a magnetic tape drive, random access memory (RAM), read only memory (ROM), or any other suitable electronic or magnetic storage mechanism.

Preferably, the comparator means takes the form of software associated with the  
20 computer. The software is preferably configured to perform a sequence of operations using the reference data and the output signal in order to generate the error signal.

Preferably, the software is also configured to enable an operator to select reference

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dimensions from a range of standard reference dimensions, contained in the storage means.

Preferably, the variation display means are disposed on or adjacent the housing to provide direct feedback of the error signal to the operator while working on the vehicle.

5        Preferably, recordal means are adapted to record the error signal in relation to the corresponding reference dimension in response to a command input by the operator, thereby to provide a permanent record of the extent of structural deviation from the manufacturer's specification, both before and after repair work has been carried out.

10        Preferably, the system further includes a remotely operable scrolling mechanism located on or adjacent the housing, to permit the operator to scroll through a range of preselected reference dimensions and to view on the variation display means a corresponding sequence of deviations while working on the vehicle.

15        Preferably, the system further includes a datum bar, a pair of first carriage assemblies slidably mounted to the datum bar, attachment means adapted releasably to secure each of said first carriage assemblies to a respective datum point on the vehicle and thereby to suspend the datum bar in a transverse orientation beneath the vehicle, and a trammel bar connected at one end to said datum bar by connection means, the connection means being adjustable to selected positions along the datum bar and permitting a degree of universal movement of the trammel bar relative to the datum bar.

20        Preferably, the housing is adapted for mounting on the trammel bar to provide measurements relative to the datum bar and hence relative to datum points on the vehicle.

Preferably, the housing further includes a slidable reference pointer adapted for connection to the vertically oriented measuring tape and adapted for engagement with selected datum points on the vehicle with the trammel bar in a horizontal orientation. In this way, the vertical tape provides a measure indicative of the vertical distance between the datum bar and the reference pointer, and the horizontal tape provides a measure of the horizontal distance between the datum bar and the reference pointer.

### BRIEF DESCRIPTION OF THE DRAWINGS

A preferred embodiment of the invention will now be described, by way of example only, with reference to the accompanying drawings in which:-

Figure 1 is a front elevation view showing a vehicle alignment gauging system according to the invention;

Figure 2 is an enlarged perspective view showing the digital measuring tapes mounted orthogonally on the housing of the system of Figure 1, according to a first embodiment of the invention;

Figure 3 is a perspective view showing the measuring tapes and housing according to a second embodiment of the invention;

Figure 4 is a perspective view showing the measuring tapes and housing together with a vertical reference pointer, according to a third embodiment of the invention;

Figure 5 shows the gauging apparatus of Figure 1 presented to the datum points on the underside of a vehicle body;

Figure 6 is a diagrammatic perspective view showing the correlation of the datum points of the vehicle shown in Figure 5;

Figure 7 shows a typical example of a data specification sheet of the type provided by vehicle manufacturers;

Figure 8 shows a sample computer screen from the system of Figure 1, as used by the operator to set up a job, input reference data, input measurement data, and compile a  
5 report; and

Figure 9 shows a sample vehicle measurement report of the type produced by the gauging system according to the invention.

#### PREFERRED EMBODIMENT OF THE INVENTION

10 Referring initially to Figures 1 and 2, the invention provides a digital vehicle alignment gauging system 1. As best seen in Figure 2, the system includes measuring means in the form of a first extendable measuring tape 2 and a second extendable measuring tape 3. The measuring tapes 2 and 3 are mounted to a housing 4, in mutually orthogonal relationship to form an integrated measuring module. The first tape 2 is  
15 generally configured to take horizontal measurements while the second tape 3 is generally configured to take vertical measurements. Each tape measure consists of a flexible steel blade 5 calibrated with visual indicia 6. Each tape is adapted to extend by unwinding from a spool which is rotatably mounted within the respective casing 7. A spring (not shown) within each housing is disposed resiliently to retract the tape by  
20 rewinding onto the spool, in conventional manner.

Output signal generation means are adapted to generate an output signal indicative of the operative or extended length of each tape. The output signal generation means ideally take the form of a position transducer, in which case the output signal takes the

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form of an electric current or voltage indicative of the extended length of the tape. In the preferred embodiment, the position transducer comprises a rotary potentiometer associated with the respective tape spool. Alternatively, however, a linear potentiometer associated with the tape blade may be used. Other alternatives include an optical reader operable in conjunction with holes punched in the tape blade, or a bar code reader in conjunction with a bar code on the tape blade. A digital vernier system or even laser distance measuring techniques may also be used. The casing 7 of each measuring tape includes an LCD screen 8, which visually displays measurements corresponding to the extended length of the tape in digital form. The output signal, as well as generating a display on the LCD screen 8, is transmitted to an RS 232 output cable 10, as described in more detail below. Alternatively, the output transmission may be achieved using an RF or infrared signal encoder, or other suitable wireless transmission means.

The system further includes storage means, preferably in the form of a portable computer 12 complete with microprocessor 13, screen 14, internal memory 15 and printer 16. The data storage mechanism associated with the computer may be a CD ROM, a floppy disk, an internal hard disk, a magnetic tape, or other suitable electronic or magnetic storage means.

The storage means are adapted to store reference data corresponding to standard dimensions for a selected vehicle, as provided by the vehicle manufacturer. An example of a typical vehicle manufacturer's data sheet is shown as Figure 7. Such data may be obtained from the manufacturer on CD ROM or the like, but may otherwise be keyed into the system manually.



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The system further includes comparator means, shown symbolically as feature 17, in the form of software loaded onto the computer. The software is configured to perform a predetermined sequence of operations which compare the output signals from the respective measuring tapes with corresponding reference dimensions stored in the  
5 computer. The software then generates an error signal indicative of the variation between the reference dimension and the corresponding dimension as actually measured.

The system further includes variation display means in the form of an LCD screen 22 on the housing or module 4. The error signal from the computer is fed to a "black box" 23 containing the signal processing circuitry within the housing, and displayed  
10 digitally on the LCD screen 22 as a variation measurement. This provides a direct quantitative indication of the degree of structural misalignment to the operator, while working on the vehicle.

The software preferably also includes a recordal function adapted to record the error signal as a variation relative to the corresponding reference dimension. This  
15 function is activated in response to an input by the operator, via the "transmit measurement" key 24 on the housing, to provide a record of the extent of initial structural deviation from the manufacturer's specification before the repair work. It also enables the operator to record the deviation after the repair work has been carried out. The function thus provides a permanent record of both the extent of initial damage and  
20 the accuracy of the subsequent repairs, as described more fully below.

The computer is connected to the printer 16, to enable the operator to produce a hard copy of the report after the repair operations have been performed. This can be used as a permanent record to confirm to the insurer and the vehicle owner that any

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deviations from the reference dimensions according to the manufacturer's specifications are within acceptable tolerances.

A scroll key 25 is also provided on the housing 4 to permit the operator to scroll through a range of preselected reference dimensions stored in the computer. Using the  
5 "variation display" key 27, the operator can also view directly on the LCD screen 22, a corresponding sequence of variation measurements while working on the vehicle.

Figures 3 and 4 show alternative embodiments and configurations of the measurement module which includes the measuring tapes, the housing, the black box containing the electronic control circuitry, and associated bracketry. Figure 4  
10 additionally shows the module as fitted with a reference pointer assembly, the operation of which will be described more fully below.

The system has been designed specifically for use in conjunction with the basic mechanical components of a vehicle alignment gauging apparatus, of the type described in Australian Patent 669,195, the full contents of which are hereby incorporated by way  
15 of cross reference. This mechanical aspect of the apparatus will not be described fully here, in view of the incorporation by cross reference. For convenience, however, the basic elements are described briefly below.

Referring to Figures 1, 5 and 6, the gauging apparatus 31 includes a transverse datum bar 32 comprising respective upper and lower flanges 33 and 34, interconnected  
20 by an intermediate web section 35. Two first carriage assemblies 40 are slidably mounted to the upper flange 33 so as to traverse the datum bar. Locking mechanisms 41 are provided to permit the carriage assemblies to be releasably secured in selected positions on the datum bar. Interchangeable attachment mechanisms 42 are adapted

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releasably to secure each carriage assembly 40 to a selected datum point on the vehicle body 46, thereby to attach the datum bar to the underside of the vehicle, usually in a generally transverse orientation.

A trammel bar 50 is connected at one end to the datum bar 32 by a connecting assembly 51. The connecting assembly comprises a trammel carriage 52 adapted  
5 slidably to traverse the lower flange 34 of the datum bar, and a universal joint 53 in the form of a double swivel. The universal joint permits independent rotation about intersecting orthogonal axes. Like the first carriages 40, the trammel carriage 52 incorporates a locking mechanism. Thus, the trammel carriage permits the proximal end  
10 of the trammel bar to be moved to and locked in selected positions along the datum bar. At the same time, the universal joint permits at least a limited degree of universal movement of the trammel bar. Adjustable end stops 54 define the limits of lateral movement of the trammel carriage on the datum bar.

The datum bar further incorporates a calibrated scale 58 displayed on the vertical  
15 web section 35. The first carriages 40 and the trammel carriage 52 incorporate respective pointers 59. The scale 58 and pointers 59 together provide indications of the relative positions of the carriages and the trammel bar on the datum bar, permitting the location of each of the carriages to be determined relative to the datum points on the vehicle.

20 The housing 4 is adapted to slide onto the remote end of the trammel bar. The square section profile of the trammel bar and the complimentary square configuration of the aperture in the housing prevents rotation of the measurement module, but permits longitudinal sliding movement along the trammel bar.

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The apparatus further includes an adjustable reference pointer assembly 62 associated with the housing 4 (see Figure 4). The reference pointer comprises an inner rod 63 slidably disposed within a tubular rod housing 64. The upper end of the rod terminates in a conical tip 67. The blade 5 of the vertical measuring tape 3 is connected  
5 to the rod housing 64 such that the tape 3 measures the vertical distance between the tip of the pointer and the trammel bar. The blade of the horizontal tape 2 is connected to the proximal end of the trammel bar, so as to measure the horizontal distance between the reference pointer and the datum bar.

The housing 4 further includes a spirit level 65 to permit the trammel bar to be  
10 levelled and oriented horizontally, with the reference pointer engaging a selected datum point on the vehicle.

Turning now to describe briefly the operation of the system, and with particular reference to Figures 1 and 5 and 6, suitable attachment fittings 42 are first selected according to the type of vehicle, the particular configuration of datum points, and the  
15 nature of the damage sustained. The selected attachment fittings are then operatively affixed to the respective carriage assemblies 40. The attachment fittings are then offered up and secured to the selected datum points, to fix the datum bar 32 in position (see Figure 5). In the majority of cases, the datum bar will be suspended in a generally horizontal orientation beneath the vehicle, transverse to the vehicle centre line.

20 The adjustable spirit level assembly is then removed from its mounting on the housing, placed on an appropriate notionally horizontal component of the vehicle such as a chassis rail, door sill or the like, and zeroed. The spirit level is then replaced on housing, which in turn is slidably mounted onto the remote end of the trammel bar. In

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this way, the spirit level is used as a surrogate level reference relative to the vehicle, so that the vehicle itself need not be precisely level. The carriage assemblies 40 are manually secured using the respective locking mechanisms 41 such that the datum bar is firmly secured relative to the selected datum points. The end stops are also secured in  
5 position such that the trammel bar is positioned directly below the respective datum points at the limits of lateral excursion. The overall length of the trammel bar can then also be adjusted telescopically to the required length having regard to the particular datum points which need to be correlated.

With the apparatus set up in this way, virtually any points on the vehicle body can  
10 be correlated. For example, to measure the horizontal distance between the datum points A and B, the carriage is first moved to abut the appropriate end stop 54 on the corresponding side of the datum bar. The end stop then locates the proximal end of the trammel bar in a zero position immediately below datum point B. The housing is then slid along the trammel bar until the reference pointer aligns with datum point A. The  
15 housing is secured in this position using grub screws 66 (Figure 2). During this process, the first measuring tape 2 unwinds from its spool and the digital display on the associated LCD screen 8 indicates the distance between datum points A and B. To measure the corresponding distance between datum points A' and B' on the other side of the vehicle, the connecting carriage 52 is simply slid along the datum bar until it abuts  
20 the end stop on the opposite side, at which point the proximal end of the trammel bar is positioned directly below datum point B'. Point B' thus becomes the new reference point for the trammel bar. The pointer 67 is then presented to the corresponding datum point A'.

By levelling the trammel bar using the spirit level in each case and adjusting the reference pointer so as to contact the respective datum point A or A', the second measuring tape 3 indicates the relative height of the pointer and hence the vertical distance between A and B, or A' and B'. This and various other measurement techniques  
5 are described in more detail in Australian Patent 669,195.

Turning now to consider the operation of the electronic aspects of the system, and referring initially to Figure 8, the manufacturer's specification for the selected vehicle is initially loaded onto the computer, typically from a CD ROM. Alternatively, the information can be entered manually from a data sheet using the interactive software.  
10 Additional information may be added, such as a job number, vehicle registration number, client name, and date. Additional reference data can also be added to account for fixed dimensional variations associated with the gauging apparatus itself. This is important if the reference planes which the manufacturer's specifications are based on are different from the reference planes inherent in the structure of the gauging apparatus.  
15 These calibration factors account for the fixed heights of the attachment mechanisms 42, and the like. The operator can also select from options to indicate whether the vehicle being measured is damaged, or repaired.

A quadrant or zone of the vehicle to be measured is then selected and defined as "A", "B", "C" or "D", as shown. The specifics of this will depend upon the nature and  
20 extent of the damage, and the structure of the software. Coordinates are then entered to define the selected datum points. Related measurements for length, width, height, and diagonals are entered according to the manufacturer's specifications. This data can either be keyed in manually by the operator from the vehicle data sheet, or extracted

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automatically by the software from specification data provided on CD ROM, or in electronic form. This information then appears on the computer screen as "vehicle data". Corresponding fields are established by the software to receive measurements from the vehicle in "damaged", and "repaired" conditions. At this stage, however, these fields are  
5 blank as shown in Figure 8. The operator then initiates the "recording" function of the software which transmits the vehicle data measurements to the module 4 on the gauging apparatus.

The operator then proceeds to measure the vehicle, one measurement at a time, using the datum bar, trammel bar, housing, and reference pointer, as described above.  
10 Using the scroll key 25 on the measurement module, the operator can scroll through and selectively display on the LCD screen 22 the preselected dimensions to be checked. Using the "variation display" key 27, the operator can display on the screen the variation between each specified dimension and the corresponding measurement. By manipulating the vehicle (using conventional panel beating and alignment techniques)  
15 until the displayed variation approaches zero, the operator can progressively rectify the structural deformations. Throughout the process, the operator is provided continuously with feedback as to the extent of misalignment, without at any stage having to move away from the measuring apparatus, or having to refer back to the computer screen or the data sheet.

20 Finally, when the variation between the actual measurement and the specified dimension has been reduced to within an acceptable tolerance, the "transmit" key 24 on the housing is used to transmit the final measurement back to the computer to compile a data report, again without the operator having to move away from the vehicle.

With the possibility for wireless transmission of data, for example using RF or infrared transmitters and receivers, there need be no physical link between the measurement module and associated structural aspects of the system, and the computer. This avoids the inconvenience and potential dangers of operators tripping over data  
5 cables. It also enables the computer and associated hardware to be positioned away from the vehicle being repaired, thereby maximising access to the vehicle. This facility also enables the expensive computer hardware to be housed securely, for example in a lockable site office, without occupying valuable space on the workshop floor.

As shown in Figure 9, the software can then be used to compile a data report,  
10 which displays in corresponding fields the vehicle reference data, the measurements from the damaged vehicle, and the measurements from the repaired vehicle. In this way, the extent of the initial damage and the final deviation if any from the manufacturer's specifications after repair are readily apparent. This report can be displayed on the computer screen or printed out as a hard copy, to be signed off by the operator as part of  
15 an insurance report.

If reference data on the vehicle is not readily available, the system can be used in comparison mode, which relies on the internal symmetry of the vehicle itself. In this mode, measurements are first taken on an undamaged portion of the vehicle and transmitted to the computer using the "transmit" control key 24 on the housing, for use  
20 as reference data. Corresponding measurements are then taken on the damaged portion of the vehicle and the difference displayed as the variation or error measurement. Repair then proceeds as described above.



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It will be appreciated from the foregoing description that the invention provides a simple, efficient and cost effective system for conducting a wide range of measurements on damaged vehicles, either by correlation to data sheets, or direct comparison of corresponding data points on the vehicle. The system displays the relevant information on the measurement module itself which also includes the principal command keys required to drive the software. This avoids the need for the operator to move away from the vehicle during the measurement and repair process. The system is thus easy to use by a single operator and can be adapted to fit on virtually any vehicle with minimal set up time. It is capable of providing both orthogonal and diagonal measurements, as well as comparative measurements in complex spatial orientations. Because the various calculations and computational steps are performed by computer, the process is greatly accelerated and the possibility of human error largely eliminated. Also of benefit is the facility enabling the operator to produce a report sheet setting out reference data, measurements from the vehicle before repair, and corresponding measurements after repair. This verifies the extent and accuracy of the work, which is often difficult and time consuming to assess after the event, once the vehicle has been reassembled. In all these respects, the invention represents a commercially significant improvement over the prior art.

Although the invention has been described with reference to specific examples, it will be appreciated by those skilled in the art that the invention may be embodied in many other forms.

## CLAIMS

1. A vehicle alignment gauging system including dimension measuring means, output  
signal generation means adapted to generate an output signal corresponding to  
dimensions indicated by the measuring means, storage means to store reference data  
5 corresponding to standard reference dimensions for a selected vehicle, comparator means  
to compare the output signal with a selected reference dimension from the storage means  
and to generate an error signal indicative of the variation therebetween, and variation  
display means to provide a visual indication of the magnitude of the variation, thereby in  
use to provide a quantitative indication of structural misalignment.
- 10 2. A system according to claim 1, wherein the measuring means include an  
extendable measuring tape, and the output signal is indicative of an operative or  
extended length of the tape.
3. A system according to claim 2, wherein said measuring tape comprises a flexible  
steel blade calibrated with visual indicia and adapted to extend by unwinding from a  
15 spool contained within a housing.
4. A system according to claim 3, further including bias means tending resiliently to  
retract the tape by rewinding onto the spool.
5. A system according claim 4, wherein the output signal generation means include a  
position transducer adapted to generate the output signal in the form of an electric  
20 current or voltage indicative of the extended length of the measuring tape.
6. A system according to claim 5, wherein the position transducer is a rotary  
potentiometer associated with the tape spool.

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7. A system according to any one of claim 6, wherein the position transducer is a linear potentiometer associated with the tape blade.
8. A system according to claim 7, further including output signal display means to display a visual indication of the extended length of the measuring tape according to the  
5 output signal, thereby to permit visual correlation between the indicia on the measuring tape and the output signal.
9. A system according to any one of claims 2 to 8, including a pair of said measuring tapes, one tape being disposed for measurement in horizontal planes and the other tape being adapted for measurement in vertical planes.
- 10 10. A system according to claim 9, wherein said measuring tapes are supported in mutually orthogonal relationship within a common housing, forming part of an integrated measurement module.
11. A system according to claim 10, wherein the output signal display means associated with each said measuring tape are disposed on or adjacent said housing.
- 15 12. A system according to any one of the preceding claims, wherein said storage means form part of a computer.
13. A system according to claim 12, wherein said storage means include one or more of a CD ROM, a floppy disk, an internal hard disk, a magnetic tape drive, random access memory (RAM) or read only memory (ROM).
- 20 14. A system according to claim 13, wherein said reference data is initially provided in CD ROM form for downloading onto a disk drive associated with the computer.

15. A system according to any one of claims 12 to 14, wherein the comparator means take the form of software configured to perform a sequence of operations using the reference data and the output signal in order to generate the error signal.
16. A system according to claim 15, wherein the software is configured to enable an operator to select a reference dimension from a range of standard reference dimensions for the vehicle from the storage means.
17. A system according to any one of claims 10 to 16, wherein the variation display means are disposed on or adjacent the housing to provide direct feedback of the error signal to the operator while working on the vehicle.
18. A system according to any one of the preceding claims, further including recordal means adapted to record the error signal in relation to the corresponding reference dimension in response to a command input by an operator, thereby to provide a record of the extent of structural deviation from specification after repair work has been carried out.
19. A system according to claim 18, wherein the recordal means include printing means adapted to produce a hard copy of a report after repair operations have been carried out, to confirm that deviations from specification are within acceptable tolerances.
20. A system according to any one of claims 10 to 19, further including a remotely operable scrolling mechanism located on or adjacent the housing, to permit an operator to scroll through a range of selected reference dimensions and to view on the variation display means a corresponding sequence of calculated variation measurements derived from the error signals while working on the vehicle.

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21. A system according to any one of the preceding claims, further including a datum bar, a pair of first carriage assemblies slidably mounted to the datum bar, attachment means adapted releasably to secure each of said first carriage assemblies to a respective datum point on the vehicle and thereby to suspend the datum bar in a transverse orientation beneath the vehicle, and a trammel bar connected at one end to said datum bar by connection means, the connection means being adjustable to selected positions along the datum bar and permitting a degree of universal movement of the trammel bar relative to the datum bar.
22. A system according to claim 21, wherein the measuring means are adapted for mounting on the trammel bar to provide measurement readings relative to the datum bar.
23. A system according to claim 22, wherein the connection means include a trammel carriage adapted to traverse the datum bar and a universal joint mounted to the trammel carriage, to permit independent relative rotation about non-parallel axes.
24. A system according to any one of claims 10 to 23, wherein said housing further includes a slidable reference pointer adapted for connection with the vertically oriented measuring tape for engagement with selected datum points on the vehicle such that with the trammel bar in a generally horizontal orientation, the vertical tape provides a measure indicative of the vertical distance between the datum bar and the reference pointer and the horizontal tape provides a measure of the horizontal distance between the datum bar and the reference pointer.
25. A system according to claim 24, further including adjustable levelling means to indicate when the trammel bar is oriented horizontally relative to the vehicle.
26. A system according to claim 25, wherein the levelling means take the form of a detachable spirit level.

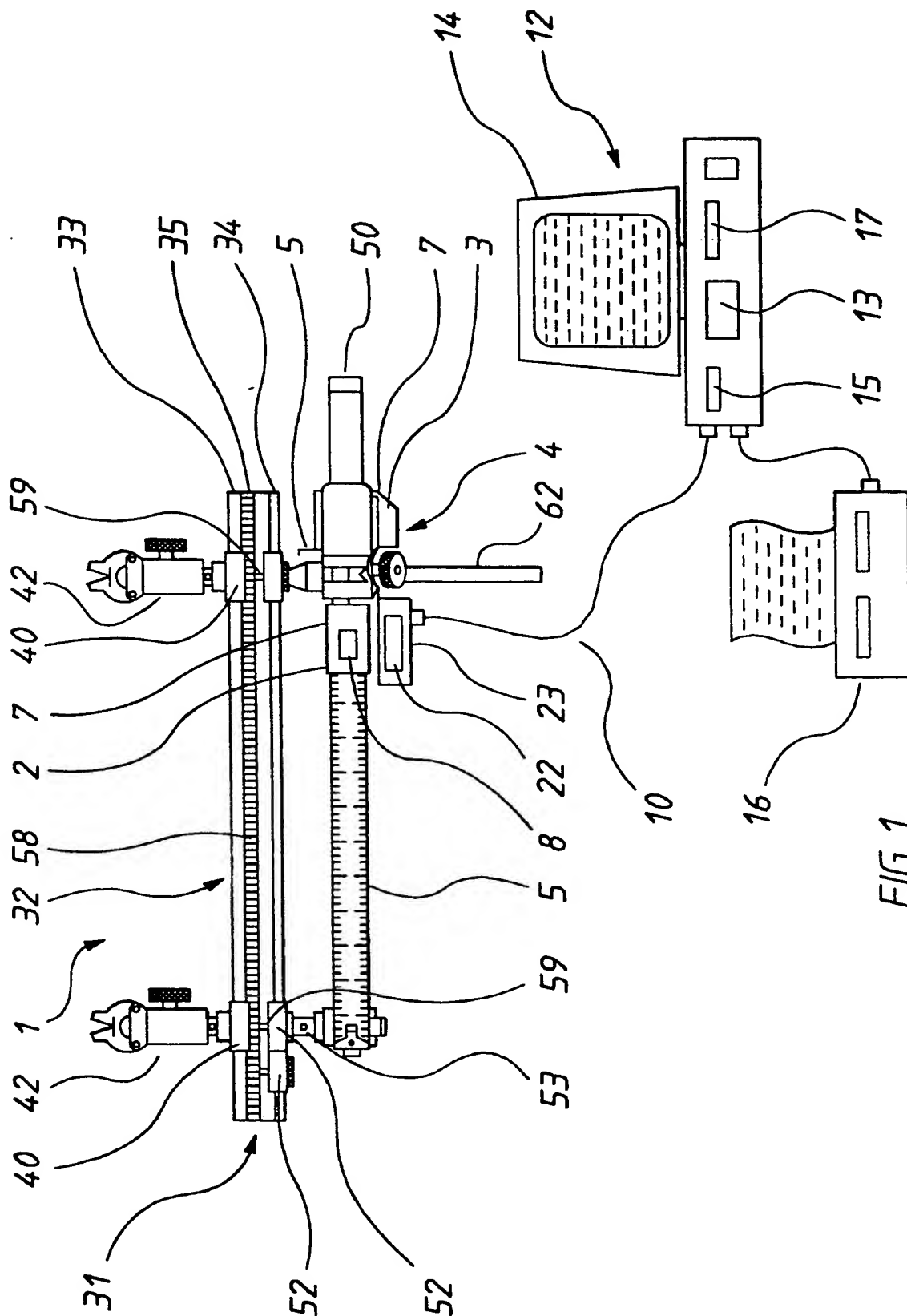


FIG. 1

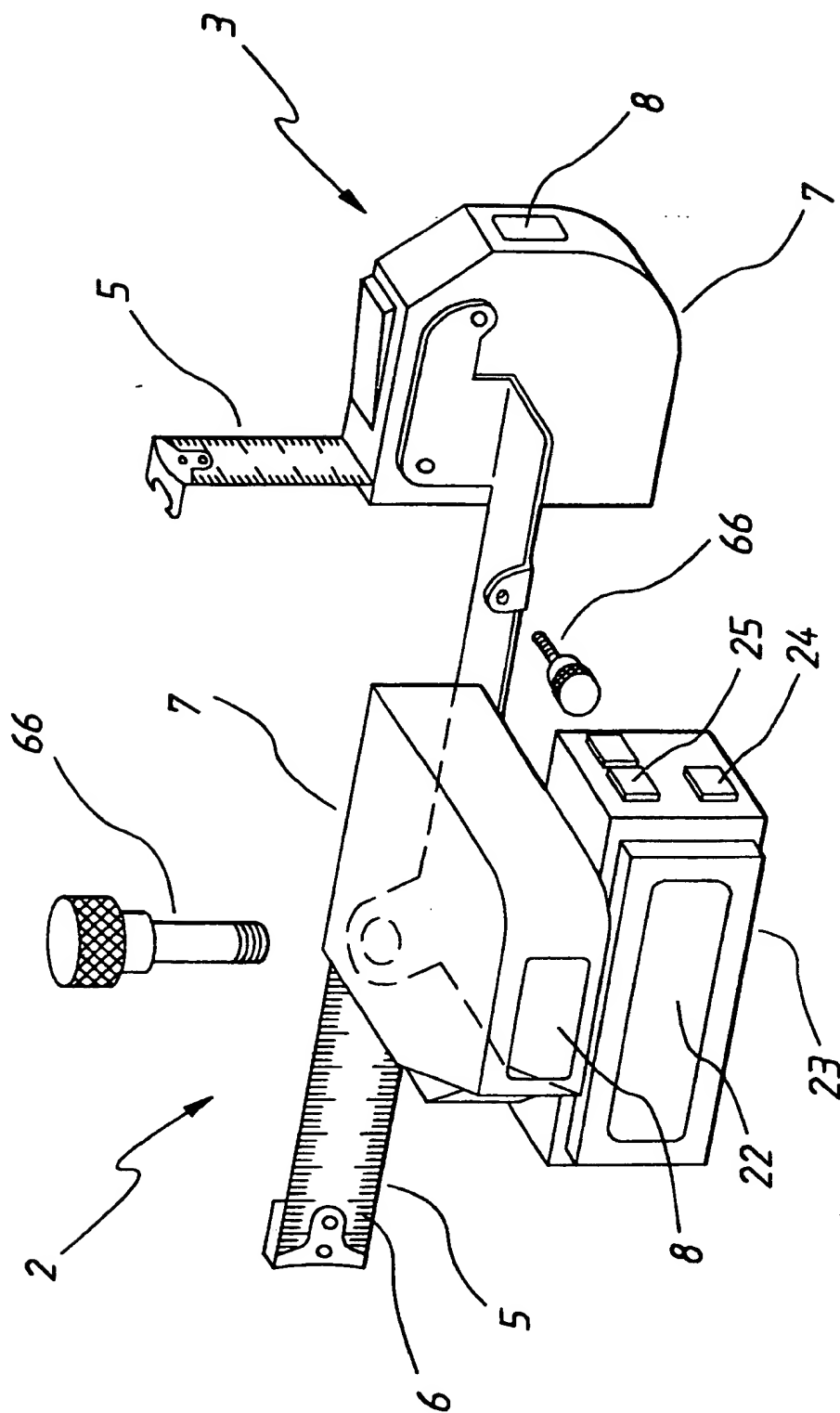


FIG. 2

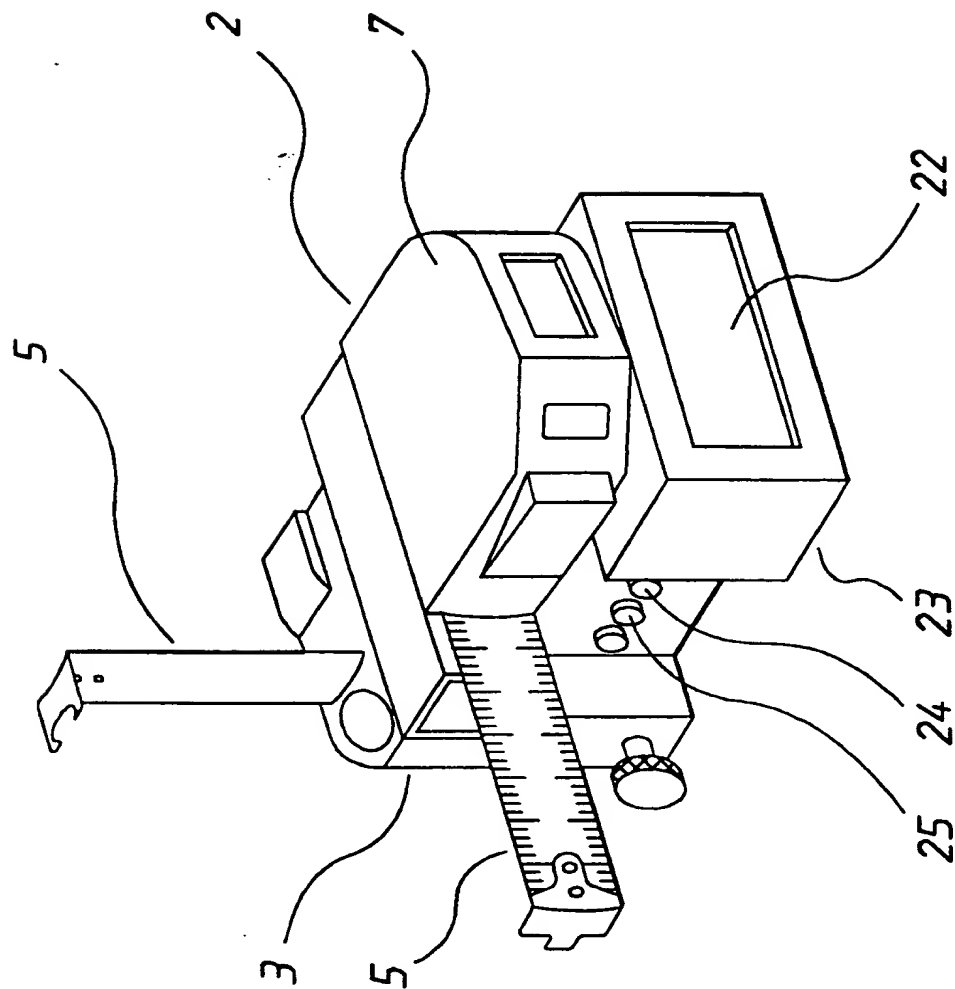
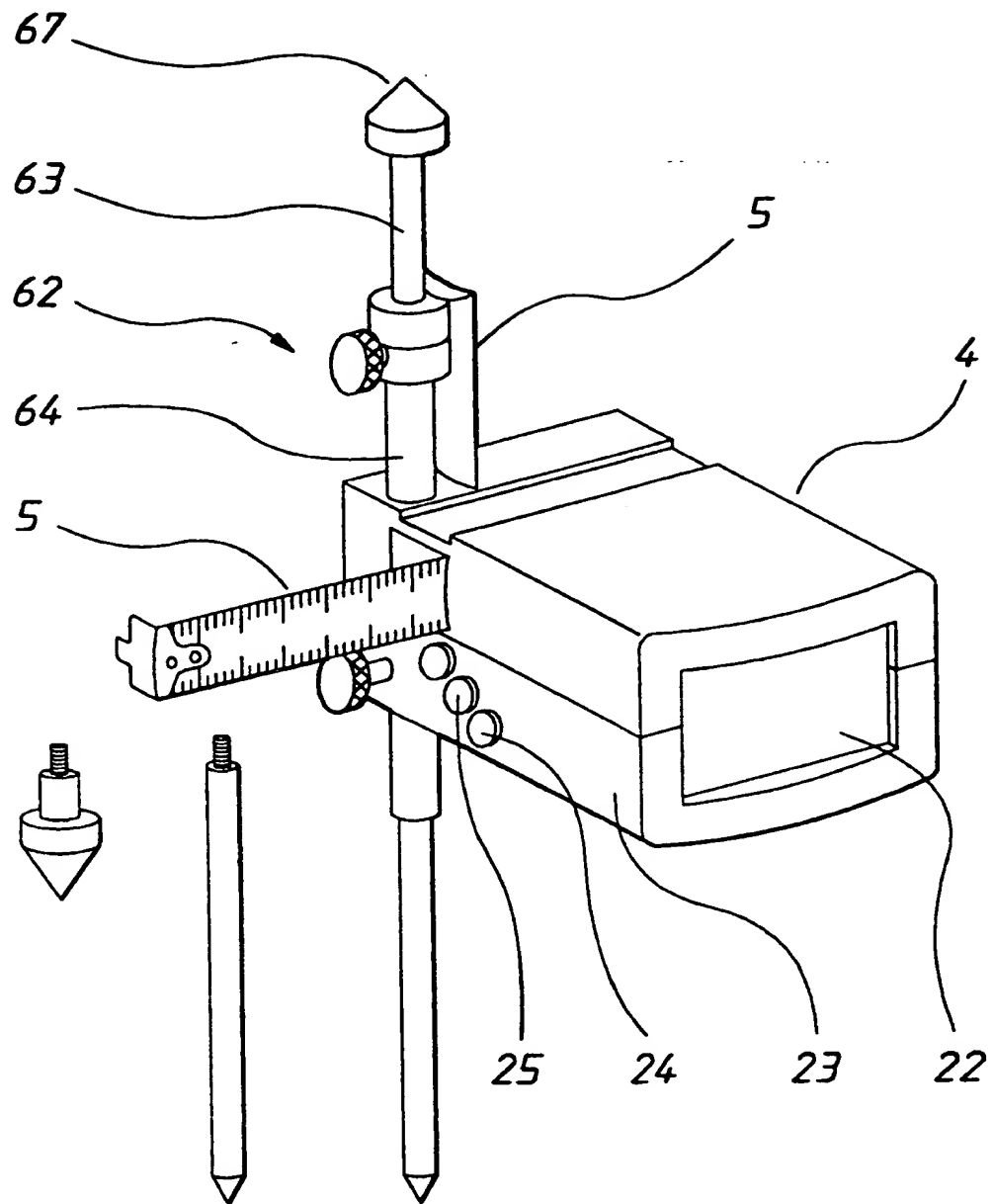


FIG. 3



FIG.4

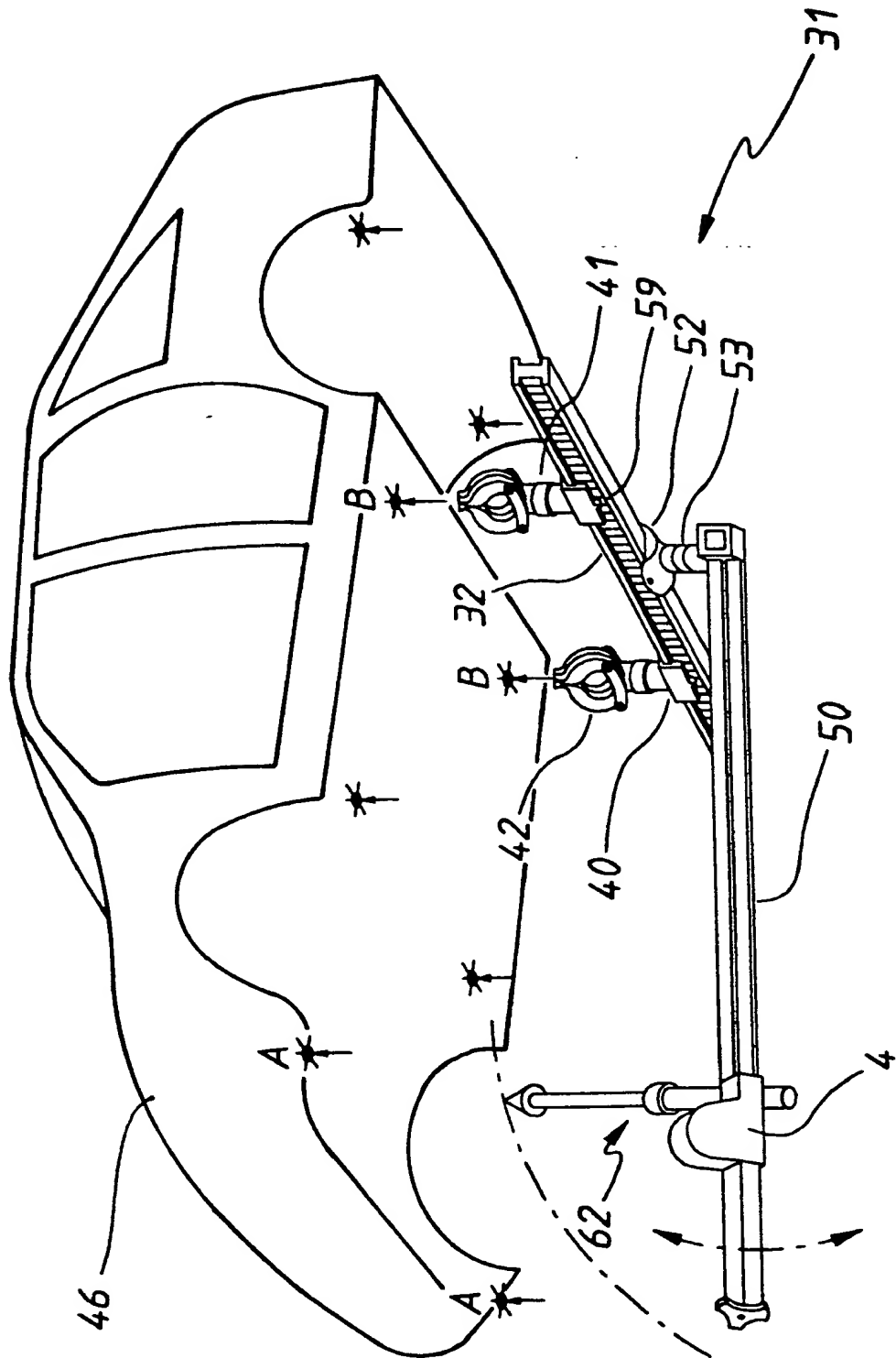


FIG. 5

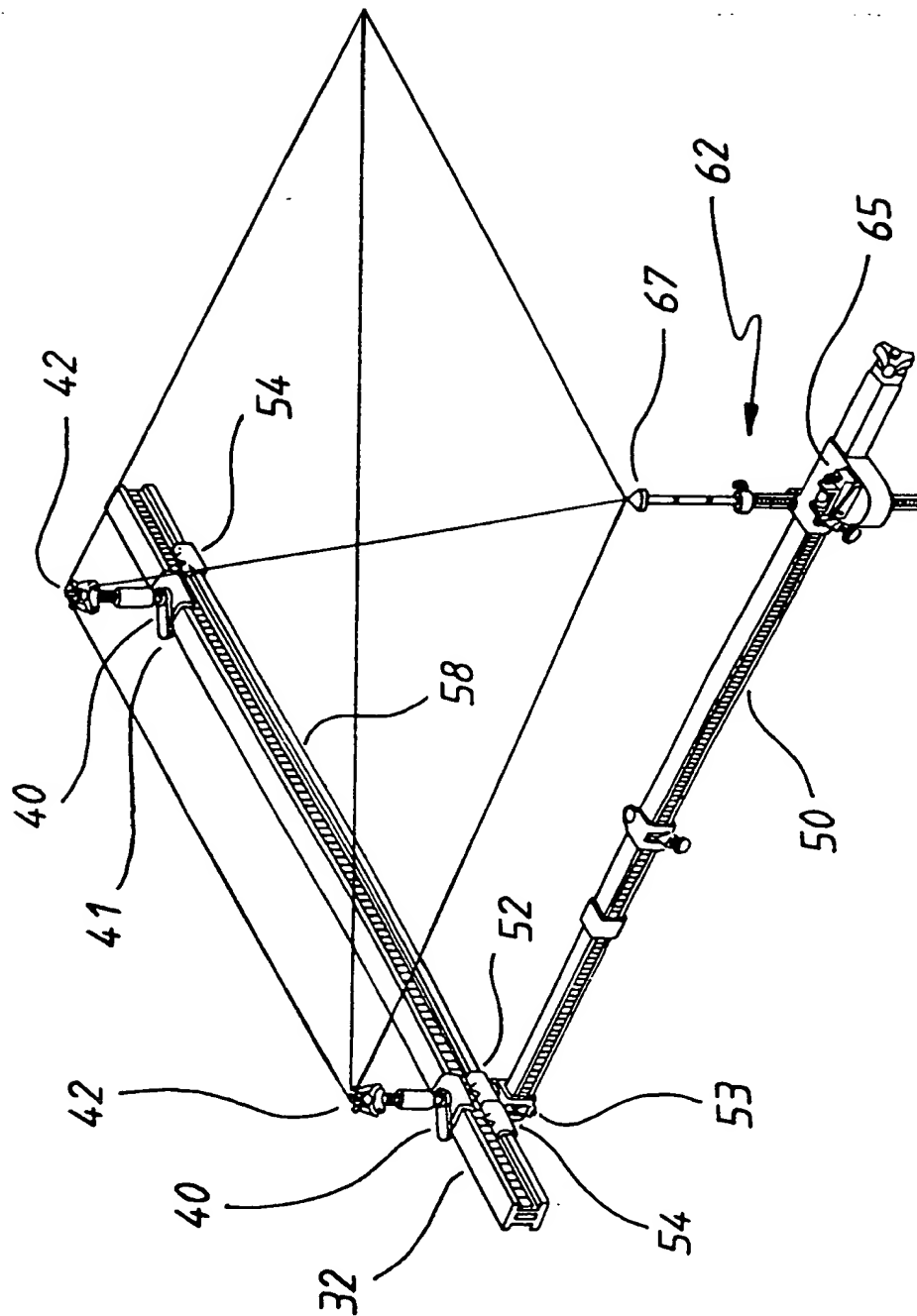


FIG. 6

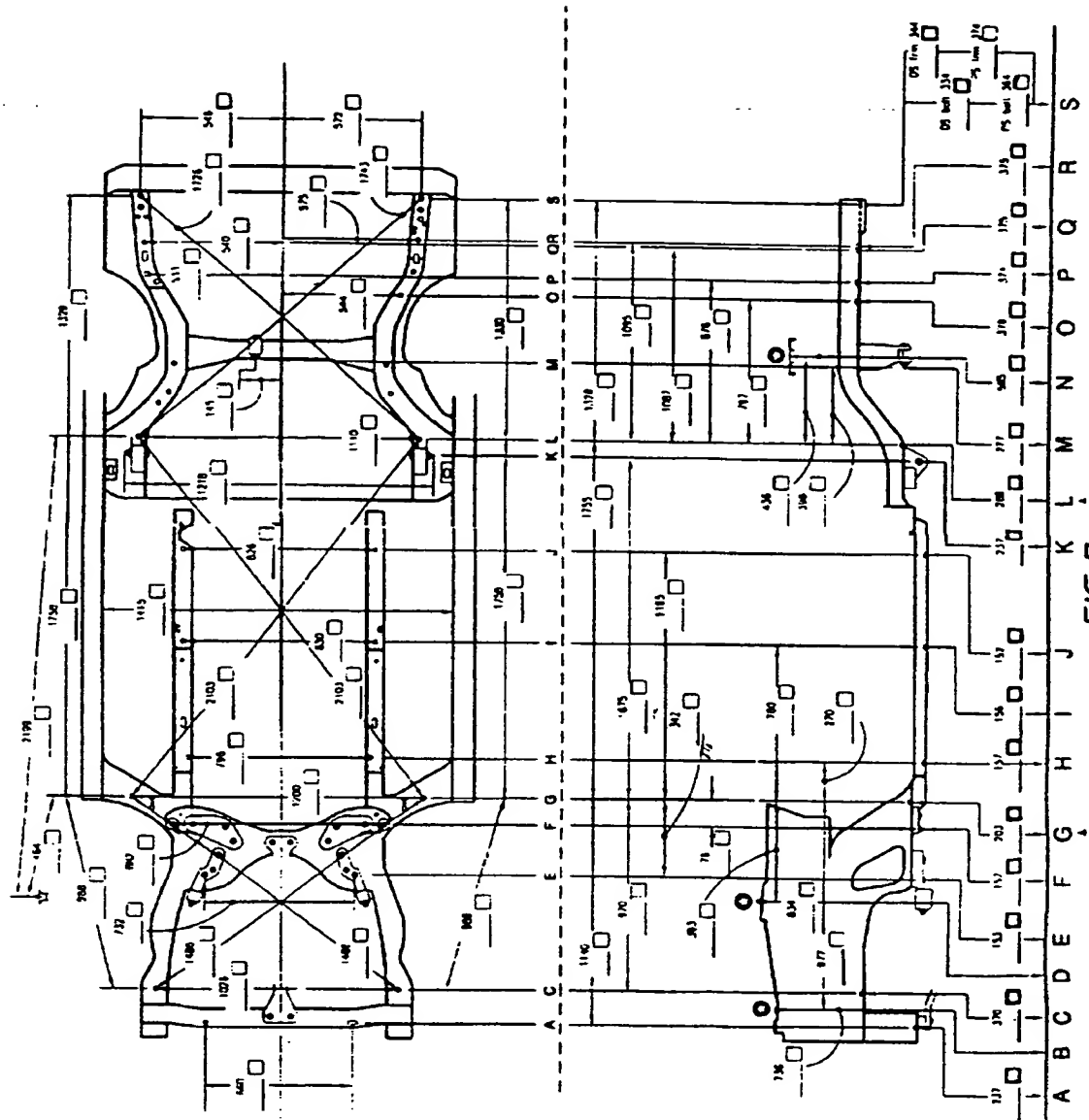


FIG. 7

**DIGI-DATA PC Controller**

**Digi Data Jobs Help**

**Edit Initial File**

Select Job:

Measure:

Vehicle:  Reg No:  Client:  Date:  File:

Active Quadrant:

Measurement Method:   Units:

	Ref	Vehicle Data		Damaged		Repaired	
		D/S	P/S	D/S	P/S	D/S	P/S
Datum Height at Cross Bar	<input type="text" value="203"/>						
Width	<input type="text" value="G"/>	<input type="text" value="1200"/>	<input type="text" value="0"/>				
Length	<input type="text" value="C"/>	<input type="text" value="970"/>	<input type="text" value="970"/>				
Height	<input type="text" value="C"/>	<input type="text" value="370"/>	<input type="text" value="370"/>				
Diagonal	<input type="text" value="C"/>	<input type="text" value="1486"/>	<input type="text" value="1486"/>				

Comment:

**Digi Data Group** **DIGI-DATA PC Controller** **3:12 pm**

FIG. 8

## VEHICLE MEASUREMENT REPORT

	VEHICLE _____ DATE: _____ REG NO: _____ JOB: _____ CLIENT: _____ FILE: _____
--	------------------------------------------------------------------------------------

DATUM HEIGHT AT CROSS BAR	A	VEH. DATA		DAMAGED		REPAIRED	
	REF	D/S	P/S	D/S	P/S	D/S	P/S
WIDTH	G	1200		0		0	
LENGTH	C	970	970	-13	0	-1	0
HEIGHT	C	370	370	-7	-1	-1	-1
DIAGONAL	C	1486	1486	-8	0	-1	0

COMMENTS: Driver side front tyre badly worn.

DATUM HEIGHT AT CROSS BAR	B	VEH. DATA		DAMAGED		REPAIRED	
	REF	D/S	P/S	D/S	P/S	D/S	P/S
WIDTH							
LENGTH							
HEIGHT							
DIAGONAL							

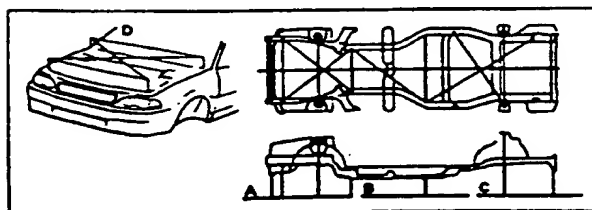
COMMENTS:

DATUM HEIGHT AT CROSS BAR	C	VEH. DATA		DAMAGED		REPAIRED	
	REF	D/S	P/S	D/S	P/S	D/S	P/S
WIDTH							
LENGTH							
HEIGHT							
DIAGONAL							

COMMENTS:

DATUM HEIGHT AT CROSS BAR	D	VEH. DATA		DAMAGED		REPAIRED	
	REF	D/S	P/S	D/S	P/S	D/S	P/S
WIDTH	A	1478		0		0	
LENGTH	B	844	844	-22	0	0	0
HEIGHT	C			89	89	89	89
DIAGONAL	D	1662	1662	-11	0	-1	0

COMMENTS:



Operator: \_\_\_\_\_

Signed: \_\_\_\_\_

Date: \_\_\_\_\_

FIG.9

## INTERNATIONAL SEARCH REPORT

International application No.

PCT/AU 98/00934

<b>A. CLASSIFICATION OF SUBJECT MATTER</b>		
Int Cl <sup>6</sup> : G01B 5/004, 5/02, 5/14, 5/25; B60S 5/00		
According to International Patent Classification (IPC) or to both national classification and IPC		
<b>B. FIELDS SEARCHED</b>		
Minimum documentation searched (classification system followed by classification symbols)		
IPC: G01B 5/004, 5/02, 5/14, 5/25; B60S 5/00		
Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched		
AU: IPC as above		
Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)		
WPAT and (VEHICLE or AUTOMO: or MOTOR or CAR) and (ALIGN: or ALIN:) and		
JAPIO with Keywords (GAUG: or GAG: or MEASURE:) and (STOR: or SAV:) and COMPAR:		
<b>C. DOCUMENTS CONSIDERED TO BE RELEVANT</b>		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 5553389 A (WINSLOW et al) 10 September 1996 column 2 line 38-column 5 line 14, Figures 1-8	1,18
X	US 5388057 A (JANUARY) 7 February 1995 abstract, column 11 lines 3-35	1,18,19
X	US 4977524 A (STREGE et al) 11 December 1990 whole document	1-5
X	US 4811250 A (STEBER et al) 7 March 1989 column 6 lines 38-44, column 7 lines 7-13, column 12 lines 23-52, Figure 1A	1,18,19
<input checked="" type="checkbox"/> Further documents are listed in the continuation of Box C <input checked="" type="checkbox"/> See patent family annex		
* Special categories of cited documents: "A" document defining the general state of the art which is not considered to be of particular relevance "E" earlier application or patent but published on or after the international filing date "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified) "O" document referring to an oral disclosure, use, exhibition or other means "P" document published prior to the international filing date but later than the priority date claimed "T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention "X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone "Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art "&" document member of the same patent family		
Date of the actual completion of the international search 4 December 1998		Date of mailing of the international search report 15 DEC 1998
Name and mailing address of the ISA/AU AUSTRALIAN PATENT OFFICE PO BOX 200 WODEN ACT 2606 AUSTRALIA Facsimile No.: (02) 6285 3929		Authorized officer  M.E. DIXON Telephone No.: (02) 6283 2194

## INTERNATIONAL SEARCH REPORT

International application No.  
PCT/AU 98/00934

C (Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 4381548 A (GROSSMAN et al) 26 April 1983 column 5 lines 25-33, Figures 1, 3D	1
X	EP 0769675 A (SNAP-ON TECHNOLOGIES, INC) 23 April 1997 whole document	1,18,19
X	EP 0566239 A (BEAR AUTOMOTIVE SERVICE) 20 October 1993 column 4 lines 5-46	1
X	Patent Abstracts of Japan, P-1607, page 163, JP 5-126559 A (NISSAN MOTOR CO LTD) 21 May 1993 abstract	1
P,A	US 5774361 A (COLARELLI, III et al) 30 June 1998 column 3 lines 50-67, column 8 lines 9-29, Figures 1, 2, 9, 10	



